

Avinashi Road, Arasur, Coimbatore.

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NBA Accredited (CSE, ECE, EEE, MECH, CIVIL)

BASICS OF ROBOTICS		
Event No	MI001	
Organizing Department	Mechatronics Engineering	
Associate Dept.   NSC	Mechatronics Engineering	
Date	19/10/2023	
Time	04:30 PM to 07:00 PM	
Event Type	Workshop	
Event Level	Dept. Level	
Venue	COE (R&A)	

## Related SDG



## Involved Staffs

SI	Name	Role
1	Balaji Arunachalam	Convenor

## Outcome

It's important to tailor the workshop to the specific needs and interests of the first-year students. The outcomes can be adjusted based on the intended learning objectives and the resources available for the workshop. Additionally, ongoing support and resources for students who wish to continue exploring robotics can be provided to further enhance their skills and knowledge in this field.

## **Event Summary**

The 'Basics of Robotics Workshop' was a one-day event organized by Department of Mechatronics Engineering at COE (R&A). The workshop aimed to introduce first-year students to the fundamental concepts and principles of robotics and automation. It was designed to provide participants with hands-on experience and a theoretical understanding of robotics technology. The workshop included informative sessions that covered the following topics: *Introduction to Robotics*: An overview of what robotics is, its history, and its applications in various industries. *Types of Robots*: An exploration of different robot types, including industrial robots, service robots, and educational robots. *Sensors and Actuators*: Discussion on the role of sensors and actuators in robotics and how they facilitate interaction with the environment. *Programming Robots*: An introduction to programming robots, including basics of coding and controlling robot movements. *Robotics Ethics and Safety*: Addressing the ethical and safety considerations in robotics technology. The participants had the opportunity to work with small educational robots provided by the organizers. They were guided by experienced trainers on: Assembling and disassembling robots Programming robots to perform simple tasks Troubleshooting common issues in robot operation



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